EE 428 : Modern Control Theory

The course covers the fundamentals of Matrix Theory including eigenvalues and eigenvectors, and the matrix representations of the Diagonal, Jordan, Controllable, and Observable forms. The student learns to represent systems in terms of their state variables and state diagrams, and then solve for their response in the time domain. The focus of the course is on linear time invariant or LTI systems. Furthermore, the controllability and observability of the LTI system is studied, before covering the design of state feedback and output feedback control techniques. In addition, observer design is covered, with the separation principle, to construct observer-based control systems.

Credits 3
Lab Hours 0
Lecture Hours 3
Tutoring Hours 0
Prerequisites
EE 306